

PARAMETERIZED COMPLEXITY OF MAXIMUM EDGE COLORABLE SUBGRAPH

A. Agrawal¹ M. Kundu² A. Sahu³ S. Saurabh^{3, 4} P.
Tale⁵

¹Ben Gurion University of the Negev, Israel.

²Indian Statistical Institute, Kolkata, India.

³The Institute of Mathematical Sciences, HBNI, Chennai, India.

⁴University of Bergen, Bergen, Norway.

⁵Max Planck Institute for Informatics, Saarland Informatics Campus, Saarbrücken,
Germany.

August 25, 2020

MAXIMUM EDGE-COLORABLE SUBGRAPH

Problem

Maximum Edge-Colorable Subgraph Problem

Input: A graph G , integers l and p .

Question: Find a subgraph H of G and a p -edge coloring of H , such that $|E(H)| \geq l$.

p -Edge Coloring of G : Function $\psi : E(G) \rightarrow \{1, 2, \dots, p\}$ s.t. any two edges having common end point receive different colors.

MAXIMUM MATCHING is a special case of MAXIMUM EDGE COLORABLE SUBGRAPH when $p = 1$.

MAXIMUM EDGE-COLORABLE SUBGRAPH

Problem

Maximum Edge-Colorable Subgraph Problem

Input: A graph G , integers l and p .

Question: Find a subgraph H of G and a p -edge coloring of H , such that $|E(H)| \geq l$.

p-Edge Coloring of G : Function $\psi : E(G) \rightarrow \{1, 2, \dots, p\}$ s.t. any two edges having common end point receive different colors.

MAXIMUM MATCHING is a special case of MAXIMUM EDGE COLORABLE SUBGRAPH when $p = 1$.

MAXIMUM EDGE-COLORABLE SUBGRAPH

Problem

Maximum Edge-Colorable Subgraph Problem

Input: A graph G , integers l and p .

Question: Find a subgraph H of G and a p -edge coloring of H , such that $|E(H)| \geq l$.

p -Edge Coloring of G : Function $\psi : E(G) \rightarrow \{1, 2, \dots, p\}$ s.t. any two edges having common end point receive different colors.

MAXIMUM MATCHING is a special case of MAXIMUM EDGE COLORABLE SUBGRAPH when $p = 1$.

MAXIMUM EDGE-COLORABLE SUBGRAPH

Problem

Maximum Edge-Colorable Subgraph Problem

Input: A graph G , integers l and p .

Question: Find a subgraph H of G and a p -edge coloring of H , such that $|E(H)| \geq l$.

p -Edge Coloring of G : Function $\psi : E(G) \rightarrow \{1, 2, \dots, p\}$ s.t. any two edges having common end point receive different colors.

MAXIMUM MATCHING is a special case of MAXIMUM EDGE COLORABLE SUBGRAPH when $p = 1$.

EXAMPLE

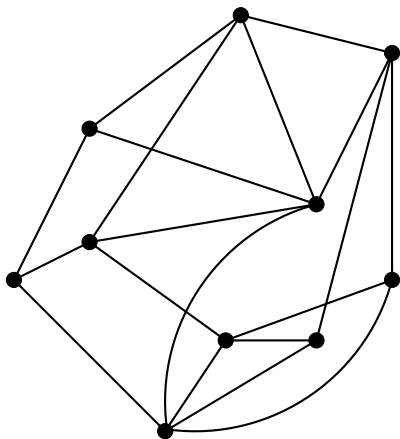


Figure: $p = 2$ and $l = 9$

EXAMPLE

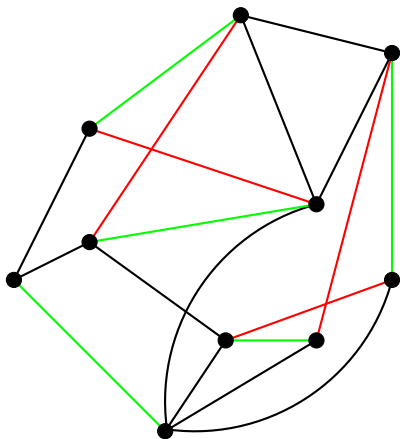


Figure: $p = 2$ and $l = 9$

OUTLINE

- Parameterized Complexity
- Known Results
- Our Contributions
- Techniques Used
- Open Questions

PARAMETERIZED COMPLEXITY

- Goal is to find better ways of solving NP-Hard problems
- Associate (small) parameter k to each instance I
- Restrict the combinatorial explosion to a parameter k
- Parameterized problem (I, k) is *fixed-parameter tractable (FPT)* if there is an algorithm that solves the problem in time $f(k) \cdot |I|^{\mathcal{O}(1)}$.

VERTEX COVER(G, k)	$\mathcal{O}(1.27^k \cdot n^2)$
FEEDBACK VERTEX SET(G, k)	$\mathcal{O}(3.46^k \cdot n^c)$
INDEPENDENT SET(G, k)	No $f(k) \cdot I ^{\mathcal{O}(1)}$

PARAMETERIZED COMPLEXITY

- Goal is to find better ways of solving NP-Hard problems
- Associate (small) parameter k to each instance I
- Restrict the combinatorial explosion to a parameter k
- Parameterized problem (I, k) is *fixed-parameter tractable (FPT)* if there is an algorithm that solves the problem in time $f(k) \cdot |I|^{\mathcal{O}(1)}$.

VERTEX COVER(G, k)	$\mathcal{O}(1.27^k \cdot n^2)$
FEEDBACK VERTEX SET(G, k)	$\mathcal{O}(3.46^k \cdot n^c)$
INDEPENDENT SET(G, k)	No $f(k) \cdot I ^{\mathcal{O}(1)}$

PARAMETERIZED COMPLEXITY

- Goal is to find better ways of solving NP-Hard problems
- Associate (small) parameter k to each instance I
- Restrict the combinatorial explosion to a parameter k
- Parameterized problem (I, k) is *fixed-parameter tractable (FPT)* if there is an algorithm that solves the problem in time $f(k) \cdot |I|^{\mathcal{O}(1)}$.

VERTEX COVER(G, k)	$\mathcal{O}(1.27^k \cdot n^2)$
FEEDBACK VERTEX SET(G, k)	$\mathcal{O}(3.46^k \cdot n^c)$
INDEPENDENT SET(G, k)	No $f(k) \cdot I ^{\mathcal{O}(1)}$

PARAMETERIZED COMPLEXITY

- Goal is to find better ways of solving NP-Hard problems
- Associate (small) parameter k to each instance I
- Restrict the combinatorial explosion to a parameter k
- Parameterized problem (I, k) is *fixed-parameter tractable (FPT)* if there is an algorithm that solves the problem in time $f(k) \cdot |I|^{\mathcal{O}(1)}$.

VERTEX COVER(G, k)	$\mathcal{O}(1.27^k \cdot n^2)$
FEEDBACK VERTEX SET(G, k)	$\mathcal{O}(3.46^k \cdot n^c)$
INDEPENDENT SET(G, k)	No $f(k) \cdot I ^{\mathcal{O}(1)}$

PARAMETERIZED COMPLEXITY

- Goal is to find better ways of solving NP-Hard problems
- Associate (small) parameter k to each instance I
- Restrict the combinatorial explosion to a parameter k
- Parameterized problem (I, k) is *fixed-parameter tractable (FPT)* if there is an algorithm that solves the problem in time $f(k) \cdot |I|^{\mathcal{O}(1)}$.

VERTEX COVER(G, k)	$\mathcal{O}(1.27^k \cdot n^2)$
FEEDBACK VERTEX SET(G, k)	$\mathcal{O}(3.46^k \cdot n^c)$
INDEPENDENT SET(G, k)	No $f(k) \cdot I ^{\mathcal{O}(1)}$

PARAMETERIZED COMPLEXITY

- Goal is to find better ways of solving NP-Hard problems
- Associate (small) parameter k to each instance I
- Restrict the combinatorial explosion to a parameter k
- Parameterized problem (I, k) is *fixed-parameter tractable (FPT)* if there is an algorithm that solves the problem in time $f(k) \cdot |I|^{\mathcal{O}(1)}$.

VERTEX COVER(G, k)	$\mathcal{O}(1.27^k \cdot n^2)$
FEEDBACK VERTEX SET(G, k)	$\mathcal{O}(3.46^k \cdot n^c)$
INDEPENDENT SET(G, k)	No $f(k) \cdot I ^{\mathcal{O}(1)}$

KERNELIZATION

- A parameterized problem admits a $h(k)$ -kernel if there is a polynomial time algorithm that reduces the input instance to an equivalent smaller instance with size upper bounded by $h(k)$.
- Goal is to bound the size of instance with some function of parameter.

VERTEX COVER(G, k)	$\mathcal{O}(k)$
FEEDBACK VERTEX SET(G, k)	$\mathcal{O}(k^3)$
INDEPENDENT SET(G, k)	No such $h(k)$

KERNELIZATION

- A parameterized problem admits a $h(k)$ -kernel if there is a polynomial time algorithm that reduces the input instance to an equivalent smaller instance with size upper bounded by $h(k)$.
- Goal is to bound the size of instance with some function of parameter.

VERTEX COVER(G, k)	$\mathcal{O}(k)$
FEEDBACK VERTEX SET(G, k)	$\mathcal{O}(k^3)$
INDEPENDENT SET(G, k)	No such $h(k)$

KERNELIZATION

- A parameterized problem admits a $h(k)$ -kernel if there is a polynomial time algorithm that reduces the input instance to an equivalent smaller instance with size upper bounded by $h(k)$.
- Goal is to bound the size of instance with some function of parameter.

VERTEX COVER(G, k)	$\mathcal{O}(k)$
FEEDBACK VERTEX SET(G, k)	$\mathcal{O}(k^3)$
INDEPENDENT SET(G, k)	No such $h(k)$

KERNELIZATION

- A parameterized problem admits a $h(k)$ -kernel if there is a polynomial time algorithm that reduces the input instance to an equivalent smaller instance with size upper bounded by $h(k)$.
- Goal is to bound the size of instance with some function of parameter.

VERTEX COVER(G, k)	$\mathcal{O}(k)$
FEEDBACK VERTEX SET(G, k)	$\mathcal{O}(k^3)$
INDEPENDENT SET(G, k)	No such $h(k)$

STRUCTURAL PARAMETERIZATION

- Associating right parameter is an art.
- Obvious choice : solution size (in this case l)
- Structural Parameters:
 - *Vertex cover number, $vc(G)$*
minimum number of vertices needed to be deleted to obtain independent set.
 - $l - mm(G)$
 $mm(G)$ is the size of a maximum matching in G .
 - *Deg-1-modulator*
For a graph G , a set $X \subseteq V(G)$ is a *deg-1-modulator* of G , if the degree of each vertex in $G - X$ is at most 1.

STRUCTURAL PARAMETERIZATION

- Associating right parameter is an art.
- Obvious choice : solution size (in this case l)
- Structural Parameters:
 - *Vertex cover number, $vc(G)$*
minimum number of vertices needed to be deleted to obtain independent set.
 - $l - mm(G)$
 $mm(G)$ is the size of a maximum matching in G .
 - *Deg-1-modulator*
For a graph G , a set $X \subseteq V(G)$ is a *deg-1-modulator* of G , if the degree of each vertex in $G - X$ is at most 1.

STRUCTURAL PARAMETERIZATION

- Associating right parameter is an art.
- Obvious choice : solution size (in this case l)
- Structural Parameters:
 - *Vertex cover number, $vc(G)$*
minimum number of vertices needed to be deleted to obtain independent set.
 - $l - mm(G)$
 $mm(G)$ is the size of a maximum matching in G .
 - *Deg-1-modulator*
For a graph G , a set $X \subseteq V(G)$ is a *deg-1-modulator* of G , if the degree of each vertex in $G - X$ is at most 1.

STRUCTURAL PARAMETERIZATION

- Associating right parameter is an art.
- Obvious choice : solution size (in this case l)
- Structural Parameters:
 - *Vertex cover number, $vc(G)$*
minimum number of vertices needed to be deleted to obtain independent set.
 - $l - mm(G)$
 $mm(G)$ is the size of a maximum matching in G .
 - *Deg-1-modulator*
For a graph G , a set $X \subseteq V(G)$ is a *deg-1-modulator* of G , if the degree of each vertex in $G - X$ is at most 1.

STRUCTURAL PARAMETERIZATION

- Associating right parameter is an art.
- Obvious choice : solution size (in this case l)
- Structural Parameters:
 - *Vertex cover number, $vc(G)$*
minimum number of vertices needed to be deleted to obtain independent set.
 - $l - mm(G)$
 $mm(G)$ is the size of a maximum matching in G .
 - *Deg-1-modulator*
For a graph G , a set $X \subseteq V(G)$ is a *deg-1-modulator* of G , if the degree of each vertex in $G - X$ is at most 1.

STRUCTURAL PARAMETERIZATION

- Associating right parameter is an art.
- Obvious choice : solution size (in this case l)
- Structural Parameters:
 - *Vertex cover number, $vc(G)$*
minimum number of vertices needed to be deleted to obtain independent set.
 - $l - mm(G)$
 $mm(G)$ is the size of a maximum matching in G .
 - *Deg-1-modulator*
For a graph G , a set $X \subseteq V(G)$ is a *deg-1-modulator* of G , if the degree of each vertex in $G - X$ is at most 1.

STRUCTURAL PARAMETERIZATION

- Associating right parameter is an art.
- Obvious choice : solution size (in this case l)
- Structural Parameters:
 - *Vertex cover number, $vc(G)$*
minimum number of vertices needed to be deleted to obtain independent set.
 - $l - mm(G)$
 $mm(G)$ is the size of a maximum matching in G .
 - *Deg-1-modulator*
For a graph G , a set $X \subseteq V(G)$ is a *deg-1-modulator* of G , if the degree of each vertex in $G - X$ is at most 1.

PROBLEM STATEMENT WITH PARAMETERS

Problem

MAXIMUM EDGE-COLORABLE SUBGRAPH PROBLEM

Input: A graph G , integers l and p .

Parameters: k where k is

- The solution size(l)
- vertex cover number, $vc(G)$
- $l - mm(G)$

Question: Find a subgraph H of G and a p -edge-coloring of H , such that $|E(H)| \geq l$.

KNOWN RESULTS

- **Vizing Theorem** : $\Delta(G) \leq \chi'(G) \leq \Delta(G) + 1$
 - $\Delta(G)$ is the maximum degree of a vertex in G
 - $\chi'(G)$ is the smallest integer p for which G is p -edge colorable (also called *chromatic index*)
- **Holyer (1981)**: Deciding chromatic index of G is $\Delta(G)$ or $\Delta(G) + 1$ is NP-Hard (even for cubic graphs).
- **Feige (2002)**: MAXIMUM EDGE COLORABLE SUBGRAPH is NP-Hard even for $p = 2$.

KNOWN RESULTS

- **Vizing Theorem** : $\Delta(G) \leq \chi'(G) \leq \Delta(G) + 1$
 - $\Delta(G)$ is the maximum degree of a vertex in G
 - $\chi'(G)$ is the smallest integer p for which G is p -edge colorable (also called *chromatic index*)
- **Holyer (1981)**: Deciding chromatic index of G is $\Delta(G)$ or $\Delta(G) + 1$ is NP-Hard (even for cubic graphs).
- **Feige (2002)**: MAXIMUM EDGE COLORABLE SUBGRAPH is NP-Hard even for $p = 2$.

KNOWN RESULTS

- **Vizing Theorem** : $\Delta(G) \leq \chi'(G) \leq \Delta(G) + 1$
 - $\Delta(G)$ is the maximum degree of a vertex in G
 - $\chi'(G)$ is the smallest integer p for which G is p -edge colorable (also called *chromatic index*)
- **Holyer (1981)**: Deciding chromatic index of G is $\Delta(G)$ or $\Delta(G) + 1$ is NP-Hard (even for cubic graphs).
- **Feige (2002)**: MAXIMUM EDGE COLORABLE SUBGRAPH is NP-Hard even for $p = 2$.

KNOWN RESULTS

- Feige (2002): A constant factor approximation algorithm. NP-Hard to get $(1 - \epsilon)$ -approximation algorithm for every fixed $p \geq 2$.
- Aloisioa and Mkrtychana (2019): The problem is FPT w.r.t. structural graph parameters like path-width, curving-width when $p = 2$.

KNOWN RESULTS

- Feige (2002): A constant factor approximation algorithm. NP-Hard to get $(1 - \epsilon)$ -approximation algorithm for every fixed $p \geq 2$.
- Aloisioa and Mkrtychana (2019): The problem is FPT w.r.t. structural graph parameters like path-width, curving-width when $p = 2$.

KNOWN RESULTS

- Feige (2002): A constant factor approximation algorithm. NP-Hard to get $(1 - \epsilon)$ -approximation algorithm for every fixed $p \geq 2$.
- Aloisioa and Mkrtychana (2019): The problem is FPT w.r.t. structural graph parameters like path-width, curving-width when $p = 2$.

KNOWN RESULTS

- Grüttemeier (2020): Obtained kernels, when the parameter is $p + k$, where k is one of the following:
 - the number of edges that needs to be deleted from G , to obtain a graph with maximum degree at most $p - 1$
 - the deletion set size to a graph whose connected components have at most p vertices
- Galby (2019): Proved EDGE COLORING is FPT when parameterized by the number of colors, (p) and the number of vertices having the maximum degree.

KNOWN RESULTS

- **Grüttemeier (2020)**: Obtained kernels, when the parameter is $p + k$, where k is one of the following:
 - the number of edges that needs to be deleted from G , to obtain a graph with maximum degree at most $p - 1$
 - the deletion set size to a graph whose connected components have at most p vertices
- **Galby (2019)**: Proved **EDGE COLORING** is FPT when parameterized by the number of colors, (p) and the number of vertices having the maximum degree.

KNOWN RESULTS

- **Grüttemeier (2020)**: Obtained kernels, when the parameter is $p + k$, where k is one of the following:
 - the number of edges that needs to be deleted from G , to obtain a graph with maximum degree at most $p - 1$
 - the deletion set size to a graph whose connected components have at most p vertices
- **Galby (2019)**: Proved **EDGE COLORING** is FPT when parameterized by the number of colors, (p) and the number of vertices having the maximum degree.

OUR CONTRIBUTION

We denote $k_1 \preceq k_2$ and say k_1 is smaller than k_2 if there exists a computable function $g(\cdot)$ such that $k_1 \leq g(k_2)$.

Observation

For a given instance (G, l, p) of MAXIMUM EDGE COLORABLE SUBGRAPH, in polynomial time, we can conclude that either (G, l, p) is a YES instance or $vc(G) \preceq l$ and $|X| \preceq (l - mm(G))$, where X is a minimum sized deg-1-modulator of G .

OUR CONTRIBUTION

Theorem

MAXIMUM EDGE COLORABLE SUBGRAPH, parameterized by the vertex cover number, $vc(G)$ of G , is FPT.

OUR CONTRIBUTION

Theorem

There exists a deterministic algorithm \mathcal{A} and a randomized algorithm \mathcal{B} with constant probability of success that solves MAXIMUM EDGE COLORABLE SUBGRAPH. For a given instance (G, l, p) , Algorithms \mathcal{A} and \mathcal{B} terminate in time $\mathcal{O}^*(4^{l+o(l)})$ and $\mathcal{O}^*(2^l)$, respectively.

OUR CONTRIBUTION

Theorem

MAXIMUM EDGE COLORABLE SUBGRAPH admits a kernel with $\mathcal{O}(kp)$ vertices, for every $k \in \{\ell, \text{vc}(G), \ell - \text{mm}(G)\}$.

Theorem

For any $k \in \{\ell, \text{vc}(G), \ell - \text{mm}(G)\}$, MAXIMUM EDGE COLORABLE SUBGRAPH does not admit a compression of size $\mathcal{O}(k^{1-\epsilon} \cdot f(p))$, for any $\epsilon > 0$ and computable function f , unless $\text{NP} \subseteq \text{coNP}/\text{poly}$.

OUR CONTRIBUTION

Theorem

MAXIMUM EDGE COLORABLE SUBGRAPH admits a kernel with $\mathcal{O}(kp)$ vertices, for every $k \in \{\ell, \text{vc}(G), \ell - \text{mm}(G)\}$.

Theorem

For any $k \in \{\ell, \text{vc}(G), \ell - \text{mm}(G)\}$, MAXIMUM EDGE COLORABLE SUBGRAPH does not admit a compression of size $\mathcal{O}(k^{1-\epsilon} \cdot f(p))$, for any $\epsilon > 0$ and computable function f , unless $\text{NP} \subseteq \text{coNP}/\text{poly}$.

TECHNIQUES USED FOR FPT PARAMETERIZED BY $\text{vc}(G)$

- For a given instance, our algorithm creates $f(\text{vc}(G))$ -many instances of ILP with nr. of variable bounded by $h(\text{vc}(G))$.
- **Kannan, Lenstra:** ILP is FPT para. by nr. of variable
- For the instance (G, l, p) , let (H, ϕ) is the solution
- X be a vertex cover of G .
- We “guess” $H' = H[X]$ and $\phi' = \phi|_{E(H')}$.
- Use ILP to find extension of this guess.

TECHNIQUES USED FOR FPT PARAMETERIZED BY $vc(G)$

- For a given instance, our algorithm creates $f(vc(G))$ -many instances of ILP with nr. of variable bounded by $h(vc(G))$.
- Kannan, Lenstra: ILP is FPT para. by nr. of variable
- For the instance (G, l, p) , let (H, ϕ) is the solution
- X be a vertex cover of G .
- We “guess” $H' = H[X]$ and $\phi' = \phi|_{E(H')}$.
- Use ILP to find extension of this guess.

TECHNIQUES USED FOR FPT PARAMETERIZED BY $vc(G)$

- For a given instance, our algorithm creates $f(vc(G))$ -many instances of ILP with nr. of variable bounded by $h(vc(G))$.
- **Kannan, Lenstra:** ILP is FPT para. by nr. of variable
- For the instance (G, l, p) , let (H, ϕ) is the solution
- X be a vertex cover of G .
- We “guess” $H' = H[X]$ and $\phi' = \phi|_{E(H')}$.
- Use ILP to find extension of this guess.

TECHNIQUES USED FOR FPT PARAMETERIZED BY $vc(G)$

- For a given instance, our algorithm creates $f(vc(G))$ -many instances of ILP with nr. of variable bounded by $h(vc(G))$.
- **Kannan, Lenstra:** ILP is FPT para. by nr. of variable
- For the instance (G, l, p) , let (H, ϕ) is the solution
 - X be a vertex cover of G .
 - We “guess” $H' = H[X]$ and $\phi' = \phi|_{E(H')}$.
 - Use ILP to find extension of this guess.

TECHNIQUES USED FOR FPT PARAMETERIZED BY $vc(G)$

- For a given instance, our algorithm creates $f(vc(G))$ -many instances of ILP with nr. of variable bounded by $h(vc(G))$.
- **Kannan, Lenstra:** ILP is FPT para. by nr. of variable
- For the instance (G, l, p) , let (H, ϕ) is the solution
- X be a vertex cover of G .
- We “guess” $H' = H[X]$ and $\phi' = \phi|_{E(H')}$.
- Use ILP to find extension of this guess.

TECHNIQUES USED FOR FPT PARAMETERIZED BY $vc(G)$

- For a given instance, our algorithm creates $f(vc(G))$ -many instances of ILP with nr. of variable bounded by $h(vc(G))$.
- **Kannan, Lenstra:** ILP is FPT para. by nr. of variable
- For the instance (G, l, p) , let (H, ϕ) is the solution
- X be a vertex cover of G .
- We “guess” $H' = H[X]$ and $\phi' = \phi|_{E(H')}$.
- Use ILP to find extension of this guess.

TECHNIQUES USED FOR FPT PARAMETERIZED BY $vc(G)$

- For a given instance, our algorithm creates $f(vc(G))$ -many instances of ILP with nr. of variable bounded by $h(vc(G))$.
- **Kannan, Lenstra:** ILP is FPT para. by nr. of variable
- For the instance (G, l, p) , let (H, ϕ) is the solution
- X be a vertex cover of G .
- We “guess” $H' = H[X]$ and $\phi' = \phi|_{E(H')}$.
- Use ILP to find extension of this guess.

TECHNIQUES USED FOR DETERMINISTIC AND RANDOMIZED ALGORITHMS

The Algorithms \mathcal{A} (deterministic algorithm) and \mathcal{B} (randomized algorithm) use different sets of ideas.

- Algorithm \mathcal{A} , uses a combination of the technique of COLOR-CODING and DIVIDE AND COLOR.
- Algorithm \mathcal{B} uses the algorithm to solve RAINBOW MATCHING as a black-box.

TECHNIQUES USED FOR DETERMINISTIC AND RANDOMIZED ALGORITHMS

The Algorithms \mathcal{A} (deterministic algorithm) and \mathcal{B} (randomized algorithm) use different sets of ideas.

- Algorithm \mathcal{A} , uses a combination of the technique of COLOR-CODING and DIVIDE AND COLOR.
- Algorithm \mathcal{B} uses the algorithm to solve RAINBOW MATCHING as a black-box.

TECHNIQUES USED FOR DETERMINISTIC AND RANDOMIZED ALGORITHMS

The Algorithms \mathcal{A} (deterministic algorithm) and \mathcal{B} (randomized algorithm) use different sets of ideas.

- Algorithm \mathcal{A} , uses a combination of the technique of COLOR-CODING and DIVIDE AND COLOR.
- Algorithm \mathcal{B} uses the algorithm to solve RAINBOW MATCHING as a black-box.

TECHNIQUES USED FOR DETERMINISTIC AND RANDOMIZED ALGORITHMS

The Algorithms \mathcal{A} (deterministic algorithm) and \mathcal{B} (randomized algorithm) use different sets of ideas.

- Algorithm \mathcal{A} , uses a combination of the technique of COLOR-CODING and DIVIDE AND COLOR.
- Algorithm \mathcal{B} uses the algorithm to solve RAINBOW MATCHING as a black-box.

TECHNIQUES USED FOR KERNEL

The technique that is used to find kernel is Expansion Lemma
t-**expansion** of P into Q is a set of edges $M \subseteq E(G)$ if (i) every vertex of P is incident with exactly t edges of M , and (ii) the number of vertices in Q which are incident with at least one edge in M is exactly $t|P|$.

Lemma: Expansion Lemma

Let t be a positive integer and G be a bipartite graph with vertex bipartition (P, Q) such that $|Q| \geq t|P|$ and there are no isolated vertices in Q . Then there exist nonempty vertex sets $P' \subseteq P$ and $Q' \subseteq Q$ such that

- P' has a t -expansion into Q'
- no vertex in Q' has a neighbour outside P' .

Furthermore two such sets P' and Q' can be found in time polynomial in the size of G .

TECHNIQUES USED FOR KERNEL

The technique that is used to find kernel is Expansion Lemma
t-**expansion** of *P* into *Q* is a set of edges $M \subseteq E(G)$ if (i) every vertex of *P* is incident with exactly *t* edges of *M*, and (ii) the number of vertices in *Q* which are incident with at least one edge in *M* is exactly $t|P|$.

Lemma: Expansion Lemma

Let *t* be a positive integer and *G* be a bipartite graph with vertex bipartition (*P*, *Q*) such that $|Q| \geq t|P|$ and there are no isolated vertices in *Q*. Then there exist nonempty vertex sets $P' \subseteq P$ and $Q' \subseteq Q$ such that

- P' has a *t*-expansion into Q'
- no vertex in Q' has a neighbour outside P' .

Furthermore two such sets P' and Q' can be found in time polynomial in the size of *G*.

TECHNIQUES USED FOR KERNEL

The technique that is used to find kernel is Expansion Lemma
t-**expansion** of P into Q is a set of edges $M \subseteq E(G)$ if (i) every vertex of P is incident with exactly t edges of M , and (ii) the number of vertices in Q which are incident with at least one edge in M is exactly $t|P|$.

Lemma: Expansion Lemma

Let t be a positive integer and G be a bipartite graph with vertex bipartition (P, Q) such that $|Q| \geq t|P|$ and there are no isolated vertices in Q . Then there exist nonempty vertex sets $P' \subseteq P$ and $Q' \subseteq Q$ such that

- P' has a t -expansion into Q'
- no vertex in Q' has a neighbour outside P' .

Furthermore two such sets P' and Q' can be found in time polynomial in the size of G .

TECHNIQUES USED: FOR KERNEL LOWER BOUNDS

- Reduction from RED BLUE DOMINATING SET (RBDS)
- Given instance (G, R, B, k) of RBDS reduction produce (G', ℓ, p) of MAXIMUM EDGE COLORABLE SUBGRAPH s.t. $\ell = |E(G)| - k$ and p is a constant.
- [Jansen and Pieterse \(2015\)](#): RBDS does not admit a compression of size $\mathcal{O}(n^{2-\epsilon})$.
- This implies the desired lower bound.

TECHNIQUES USED: FOR KERNEL LOWER BOUNDS

- Reduction from RED BLUE DOMINATING SET (RBDS)
- Given instance (G, R, B, k) of RBDS reduction produce (G', ℓ, p) of MAXIMUM EDGE COLORABLE SUBGRAPH s.t. $\ell = |E(G)| - k$ and p is a constant.
- Jansen and Pieterse (2015): RBDS does not admit a compression of size $\mathcal{O}(n^{2-\epsilon})$.
- This implies the desired lower bound.

TECHNIQUES USED: FOR KERNEL LOWER BOUNDS

- Reduction from RED BLUE DOMINATING SET (RBDS)
- Given instance (G, R, B, k) of RBDS reduction produce (G', ℓ, p) of MAXIMUM EDGE COLORABLE SUBGRAPH s.t. $\ell = |E(G)| - k$ and p is a constant.
- Jansen and Pieterse (2015): RBDS does not admit a compression of size $\mathcal{O}(n^{2-\epsilon})$.
- This implies the desired lower bound.

TECHNIQUES USED: FOR KERNEL LOWER BOUNDS

- Reduction from RED BLUE DOMINATING SET (RBDS)
- Given instance (G, R, B, k) of RBDS reduction produce (G', ℓ, p) of MAXIMUM EDGE COLORABLE SUBGRAPH s.t. $\ell = |E(G)| - k$ and p is a constant.
- [Jansen and Pieterse \(2015\)](#): RBDS does not admit a compression of size $\mathcal{O}(n^{2-\epsilon})$.
- This implies the desired lower bound.

TECHNIQUES USED: FOR KERNEL LOWER BOUNDS

- Reduction from RED BLUE DOMINATING SET (RBDS)
- Given instance (G, R, B, k) of RBDS reduction produce (G', ℓ, p) of MAXIMUM EDGE COLORABLE SUBGRAPH s.t. $\ell = |E(G)| - k$ and p is a constant.
- [Jansen and Pieterse \(2015\)](#): RBDS does not admit a compression of size $\mathcal{O}(n^{2-\epsilon})$.
- This implies the desired lower bound.

OPEN QUESTIONS

We showed –

- Kernel with $\mathcal{O}(kp)$ vertices for $k \in \{l, \text{vc}, l - \text{mm}(G)\}$
- No kernel of size $\mathcal{O}(k^{1-\epsilon} f(p))$.

Q Can we bridge the gap?

Problem is NP-Hard on regular graphs of degree $p + 1$.

For such graphs classes, kernel lower bound is tight.

OPEN QUESTIONS

We showed –

- FPT when para. by vc
- FPT when para. by ℓ
- Admits a polynomial kernel when para. by ℓ

Q Is it FPT when para. by $\ell - \text{mm}(G)$?

Q Does it admits a polynomial kernel when parameterized by vc ?

Thank You!